ONLINE APPENDIX: OMITTED PROOFS FOR RESULTS IN
“OPTIMAL PROVISION OF MULTIPLE EXCLUDABLE PUBLIC GOODS”
FANG AND NORMAN (2010)

A Relevant Material from Fang and Norman (2006a) Referenced in the Paper

A.1 The Environment

There are \( M \) excludable and indivisible public goods, labeled by \( j \in J = \{1, \ldots, M\} \) and \( n \) agents, indexed by \( i \in I = \{1, \ldots, n\} \). The cost of providing good \( j \), denoted \( C^j(n) \), is independent of which of the other goods are provided. Notice that \( C^j(n) \) depends on \( n \), the number of agents in the economy, and not on the number of users. This assumption captures the fully non-rival nature of the public goods. Indexing the cost by \( n \) also enables us to analyze large economies without making the public goods a “free lunch” in the limit. We therefore assume that \( \lim_{n \to \infty} C^j(n)/n = c^j > 0. \)

Agent \( i \) is described by a valuation for each good \( j \in J \). Her type is given by a vector \( \theta_i = (\theta_i^1, \ldots, \theta_i^M) \in \Theta \subset \mathbb{R}^M \), and her preferences are represented by the utility function,

\[
\sum_{j \in J} I^j_i \theta^j_i - t_i, \tag{B1}
\]

where \( I^j_i \) is a dummy variable taking value 1 when \( i \) consumes good \( j \) and 0 otherwise, and \( t_i \) is the quantity of the numeraire good transferred from \( i \) to the mechanism designer. Preferences over lotteries are of the expected utility form.

The type \( \theta_i \) is private information to agent \( i \). Unlike much of the bundling literature, valuations for different goods for any agent are allowed to be correlated. However, types are independent across agents. We denote by \( F \) the joint cumulative distribution over \( \theta_i \). For brevity of notation, we denote a generic type profile by \( \theta \equiv (\theta_1, \ldots, \theta_n) \in \Theta^n \). In the usual fashion, we let \( \theta_{-i} = (\theta_1, \ldots, \theta_{i-1}, \theta_{i+1}, \ldots, \theta_n) \).

A.2 Mechanisms

An outcome in our environment has three components: (1) which goods, if any, should be provided; (2) who are to be given access to the goods that are provided; and (3) how to share the costs. The set of feasible pure outcomes is thus

\[
A = \{0,1\}^M \times \{0,1\}^{M \times n} \times \mathbb{R}^n. \tag{B2}
\]

By the revelation principle, we only consider direct mechanisms for which truth-telling is a Bayesian Nash equilibrium. A pure direct mechanism maps \( \Theta^n \) onto \( A \), and a randomized mechanism is represented in analogy with the representation of mixed strategies in Aumann (1964). That is, let \( \Xi \equiv [0,1] \) and think of \( \vartheta \in \Xi \) as the outcome of a fictitious lottery where, without loss of generality, \( \vartheta \) is uniformly distributed and independent of \( \theta \). A random direct mechanism is then a measurable mapping \( G : \Theta^n \times \Xi \to A \). A

\( ^1 \)There is no need to give this assumption any economic interpretation. It is best viewed as a way to ensure that the public good provision problem remains “significant” when there are a large number of agents.
conceptual advantage of this representation is that it allows for a useful decomposition in the sense that we now may write \( \mathcal{G} = (\{\zeta^j\}_{j \in J}, \{\omega^j\}_{j \in J}, \tau) \) where

\[
\begin{align*}
\text{Provision Rule:} & \quad \zeta^j : \Theta^n \times \Xi \to \{0, 1\} \\
\text{Inclusion Rule:} & \quad \omega^j : \Theta^n \times \Xi \to \{0, 1\}^n \\
\text{Cost-sharing Rule:} & \quad \tau : \Theta^n \to \mathbb{R}^n.
\end{align*}
\]

We refer to \( \zeta^j \) as the provision rule for good \( j \), and interpret \( \mathbb{E}_{\Xi} \zeta^j (\theta, \vartheta) \) as the probability of provision for good \( j \) given announcements \( \theta \). The rule \( \omega^j = (\omega^j_1, \ldots, \omega^j_n) \) is the inclusion rule for good \( j \), and \( \mathbb{E}_{\Xi} \omega^j_i (\theta, \vartheta) \) is interpreted as the probability that agent \( i \) gets access to good \( j \) when announcements are \( \theta \), conditional on good \( j \) being provided. Finally, \( \tau = (\tau_1, \ldots, \tau_n) \) is the cost-sharing rule, where \( \tau_i (\theta) \) is the transfer from agent \( i \) to the mechanism designer given announced valuation profile \( \theta \). In principle, transfers could also be random, but the pure cost-sharing rule in (B3) is without loss of generality due to risk neutrality.

### A.3 The Design Problem

Let \( E_{-i} \) denote the expectation operator with respect to \( (\theta_{-i}, \vartheta) \). A mechanism is incentive compatible if truth-telling is a Bayesian Nash equilibrium in the revelation game induced by \( \mathcal{G} \), i.e., \( \forall i \in I, \theta \in \Theta^n, \hat{\theta}_i \in \Theta \),

\[
E_{-i} \left[ \sum_{j \in J} \zeta^j (\theta, \vartheta) \omega^j_i (\theta, \vartheta) \vartheta^j_i - \tau_i (\theta) \right] \geq E_{-i} \left[ \sum_{j \in J} \zeta^j (\hat{\theta}_i, \theta_{-i}, \vartheta) \omega^j_i (\hat{\theta}_i, \theta_{-i}, \vartheta) \vartheta^j_i - \tau_i (\hat{\theta}_i, \theta_{-i}) \right].
\]

We also require that the project be self-financing. For simplicity, this is imposed as an ex ante balanced-budget constraint:

\[
E \left( \sum_{i \in I} \tau_i (\theta) - \sum_{j \in J} \zeta^j (\theta, \vartheta) \omega^j_i C^j (n) \right) \geq 0.
\]

Non-rival nature of the public goods is built into (BB) because the cost depends only on the provision probabilities \( \zeta^j (\theta, \vartheta) \), and not on the inclusion probabilities \( \omega^j_i (\theta, \vartheta) \). Finally, we require that a voluntary participation, or individual rationality, condition be satisfied. Individual rationality is imposed at the interim stage as:

\[
E_{-i} \left[ \sum_{j \in J} \zeta^j (\theta, \vartheta) \omega^j_i (\theta, \vartheta) \vartheta^j_i - \tau_i (\theta) \right] \geq 0, \quad \forall i \in I, \theta_i \in \Theta.
\]

A mechanism is incentive feasible if it satisfies (IC), (BB) and (IR). Because utility is transferable, constrained ex ante Pareto efficient allocations solve a utilitarian planning problem, where a fictitious social planner seeks to maximize social surplus subject to the constraints (IC), (BB) and (IR).\(^3\) Thus a mechanism is constrained efficient if it maximizes

\[
\sum_{j \in J} \mathbb{E} \zeta^j (\theta, \vartheta) \left[ \sum_{i \in I} \omega^j_i (\theta, \vartheta) \vartheta^j_i - C^j (n) \right],
\]

\(^2\)As shown in Borgers and Norman (2008) it is without loss of generality to consider a resource constraint in ex ante form.

\(^3\)The qualifier ex ante is crucial for the equivalence. See Ledyard and Palfrey (2007) for a characterization of interim efficiency.
over all incentive feasible mechanisms. 4

Ex post efficiency requires that good \( j \) be provided if and only if \( \sum_{i \in I} \theta_i^j \geq C^j(n) \), and that all agents receive full access whenever a good is provided. Since the ex post efficient allocation requires that no agent be excluded from usage, it is implementable if and only if a non-excludable public good can be efficiently provided under (IC), (BB) and (IR). But we know from Mailath and Postlewaite (1990) that this is impossible except for trivial cases. Our setup is thus a second best problem.

A.4 Simple Anonymous Mechanisms

We now consider mechanisms that are less complex than general mechanisms formulated in (B3).

Definition 2 A mechanism is called a simple mechanism if it can be expressed as a \((2M + 1)\)-tuple \( g = (\rho, \eta, t) \equiv (\{\rho^j\}_{j \in J}, \{\eta^j\}_{j \in J}, t) \) such that for each good \( j \in J \),

- **Provision Rule:** \( \rho^j : \Theta^n \rightarrow [0, 1] \)
- **Inclusion Rule:** \( \eta^j : \Theta \rightarrow [0, 1] \) \hspace{1cm} (B5)
- **Cost-sharing Rule:** \( t : \Theta \rightarrow R \),

where \( \rho^j \) is the provision rule for good \( j \), \( \eta^j \) is the inclusion rule for good \( j \), and \( t \) is the transfer rule, same for all agents.

Definition 3 A simple mechanism is called anonymous if for every \( j \in J \), \( \rho^j(\theta) = \rho^j(\theta') \) for every \((\theta, \theta') \in \Theta^n \times \Theta^n\) such that \( \theta' \) can be obtained from \( \theta \) by permuting the indices of the agents.

Simple mechanisms of the form (B5) are less complex than general direct revelation mechanisms of the form (B3) in several ways. First, inclusion and transfer rules are the same for all agents. Second, conditional on \( \theta \), the provision probability \( \rho^j(\theta) \) is independent of all other provision probabilities as well as all inclusion probabilities. Third, the inclusion and transfer rules for any agent \( i \) are independent of \( \theta_{-i} \). Finally, all agents are treated symmetrically in terms of the transfer and inclusion rules. However, simple mechanisms as defined in (B5) do allow for asymmetric treatment of the agents in terms of the provision rule, which is why we introduce the notion of anonymous mechanisms in Definition 3.

Our first results show that focusing on simple anonymous mechanisms is without loss of generality:

**Proposition 1 (Fang and Norman 2006a).** For any incentive feasible mechanism \( G \) of the form (B3), there exists a simple anonymous incentive feasible mechanism \( g \) that generates the same social surplus.

The rough idea for Proposition 1 is as follows. Risk neutral agents care only about the perceived probability of consuming each good and the expected transfer. Therefore, there is nothing to gain from conditioning transfers and inclusion probabilities on \( \theta_{-i} \), or by making inclusion and provision rules conditionally dependent. Mechanisms on form (B5) are therefore sufficient. Moreover, given an incentive

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4 All these constraints are noncontroversial if the design problem is interpreted as a private bargaining agreement. If the goods are government provided, the participation constraints (IR) may seem questionable. One defense in this context is that the participation constraint is a reduced form of an environment where agents may “vote with their feet.” Another defense is to view this as a reduced form for inequality aversion of the planner (see Hellwig 2005).
feasible mechanism, permuting the roles of the agents leaves the surplus unchanged and all constraints satisfied. Thus an anonymous incentive feasible mechanism that generates the same surplus as the initial mechanism can be obtained by averaging over the $n!$ permuted mechanisms.\footnote{The proof is more complex than simply randomizing with equal probabilities over the $n!$ permutations because inclusion and provision probabilities can be correlated.}

### A.5 Symmetric Treatment of the Goods

Our next result, on which we rely heavily in Sections 3 and 4, identifies sufficient conditions under which it is without loss of generality to treat goods symmetrically. Given valuation profile $\theta$ and a one-to-one permutation mapping of the goods $P: \mathcal{J} \rightarrow \mathcal{J}$ with inverse $P^{-1}$, let $\theta_i^P = (\theta_i^{P^{-1}(1)}, \theta_i^{P^{-1}(2)}, ..., \theta_i^{P^{-1}(M)})$ denote the permutation of agent $i$’s type by changing the role of the goods in accordance to $P$. The valuation profile obtained when the role of the goods is changed in accordance to $P$ for every $i \in \mathcal{I}$ is denoted by $\theta^P \equiv (\theta_1^P, ..., \theta_n^P)$.

**Definition 4** Mechanism $g$ is symmetric if for every $\theta$ and every permutation $P: \mathcal{J} \rightarrow \mathcal{J}$,

1. $\rho^{P^{-1}(j)}(\theta^P) = \rho^j(\theta)$ for every $j \in \mathcal{J}$;
2. $\eta^{P^{-1}(j)}(\theta_i^P) = \eta^j(\theta_i)$ for every $j \in \mathcal{J}$;
3. $t(\theta_i^P) = t(\theta_i)$.

Note that in the definition of a symmetric mechanism, the same permutation of goods is applied for all agents.\footnote{As an example, suppose that there are two agents and two goods, and that the valuation for each good is either $h$ or $l$. In this case $\Theta = \{(h, h), (h, l), (l, h), (l, l)\}$. Consider the type profile $\theta = (\theta_1, \theta_2) = ((h, l), (l, h)) \in \Theta^2$. Applying the only non-identity permutation of the goods, i.e., $P(1) = 2$ and $P(2) = 1$, to all agents generates a type profile $\theta'^P = (\theta_1'^P, \theta_2'^P) = ((l, h), (h, l))$. Definition 4 requires that the allocations for type profile $((l, h), (h, l))$ is the same as the allocation for $((h, l), (l, h))$ with goods relabeled and transfers unchanged.}

Clearly, the environment must be symmetric if there is to be any hope for symmetric solutions. First, provision costs need to be identical across goods, i.e. $C^j(n) = C(n)$ for all $j$. Second, some symmetry assumption on valuations is also necessary. Symmetry of valuations is imposed by requiring that $\theta_i = (\theta_1^i, ..., \theta_M^i)$ is an exchangeable random vector, which means that $F(\theta_i) = F(\theta_i')$ if $\theta_i'$ is a permutation of $\theta_i$. Notice that this still allows for valuations to be correlated.

Under these restrictions it is without loss of generality to consider symmetric mechanisms:

**Proposition 2 (Fang and Norman 2006a).** Suppose that $\theta_i$ is an exchangeable random vector and $C^j(n) = C(n)$ for all $j \in \mathcal{J}$. Then, for any simple anonymous incentive feasible mechanism $g$, there exists a symmetric simple anonymous incentive feasible mechanism that generates the same surplus as $g$. The idea is similar to that of Proposition A.4, except that it is the roles of the goods that are permuted. For intuition, consider the case with two goods, and suppose that the two goods are treated asymmetrically. Reversing the role of the goods, an alternative mechanism that generates the same surplus is obtained. Averaging over the original and the reversed mechanism creates a symmetric mechanism.
where surplus is unchanged.\footnote{Provision probabilities and taxes are given by straightforward averaging, but since inclusion and provision probabilities may be correlated the procedure is somewhat more involved for the inclusion rules.} Incentive feasibility of the new mechanism follows from incentive feasibility of the original mechanism. The proof of Proposition A.5 generalizes this procedure by permuting the goods ($M!$ possibilities) and creating a symmetric mechanism by averaging over these permuted mechanisms.

**PROOF OF PROPOSITION 2:** The proposition follows from the following Claims B1 and B2 below.

**Claim B1** For any incentive feasible mechanism $G$ of the form (B3), there exist an incentive feasible mechanism

$$G = \left( \left( \rho_j^i, \eta_j^i \right)_{j \in J}, (t_i)_{i \in I} \right),$$

(B6)

that generates the same social surplus, where $\rho_j^i : \Theta^n \rightarrow [0,1]$ is the provision rule for good $j$, $\eta_j^i : \Theta \rightarrow [0,1]$ is the inclusion rule for agent $i$ and good $j$, and $t_i : \Theta \rightarrow R$ is the transfer rule for agent $i$.

To see this, consider an incentive feasible mechanism $G$. Pick any $k \in [0,1]$ and define, for each $\theta \in \Theta^n$, $j \in J$ and $i \in I$,

$$\rho_j^i (\theta) = E_{\Xi} \zeta_j^i (\theta, \vartheta) = \int_0^1 \zeta_j^i (\theta, \vartheta) d\vartheta$$

(B7)

$$\eta_j^i (\theta) = \begin{cases} \frac{\int_{\Theta^n} \int_0^1 \zeta_j^i (\theta, \vartheta) \omega_j^i (\theta, \vartheta) d\vartheta dF(\theta_{-i})}{\int_{\Theta^n} \int_0^1 \zeta_j^i (\theta, \vartheta) d\vartheta dF(\theta_{-i})} & \text{if } \int_{\Theta^n} \int_0^1 \zeta_j^i (\theta, \vartheta) d\vartheta dF(\theta_{-i}) > 0 \\ \frac{0}{0} & \text{if } \int_{\Theta^n} \int_0^1 \zeta_j^i (\theta, \vartheta) d\vartheta dF(\theta_{-i}) = 0 \end{cases}$$

$$t_i (\theta) = E_{-i} \tau_j^i (\theta) = \int_{\Theta^n} \tau_j^i (\theta) dF(\theta_{-i}).$$

This is a mechanism of the form in (B6), and we will call it $G$. Use of the law of iterated expectations on $\rho_j^i (\theta)$ and $t_i (\theta)$ shows that (BB) is unaffected when switching from $G$ to $G$. It remains to show that the surplus is unchanged, and that (IC) and (IR) continue to hold under $G$. The utility of agent $i$ of type $\theta_i \in \Theta$ who announces $\hat{\theta}_i \in \Theta$

$$E_{-i} \left[ \sum_{j \in J} \zeta_j^i \left( \hat{\theta}_i, \theta_{-i}, \vartheta \right) \omega_j^i \left( \hat{\theta}_i, \theta_{-i}, \vartheta \right) \theta_i - \tau \left( \hat{\theta}_i, \theta_{-i} \right) \right]$$

(B8)

$$E_{-i} \left[ \sum_{j \in J} \rho_j^i \left( \hat{\theta}_i, \theta_{-i} \right) \eta_j^i \left( \hat{\theta}_i \right) \theta_i - t_i \left( \hat{\theta}_i \right) \right]$$

(B9)

If $\int_{\Theta^n} \int_0^1 \zeta_j^i \left( \hat{\theta}_i, \theta_{-i}, \vartheta \right) d\vartheta dF(\theta_{-i}) = 0$, we trivially have that the payoffs in (B8) and (B9) are identical, whereas if $\int_{\Theta^n} \int_0^1 \zeta_j^i \left( \hat{\theta}_i, \theta_{-i}, \vartheta \right) d\vartheta dF(\theta_{-i}) > 0$, we have that

$$E_{-i} \rho_j^i \left( \hat{\theta}_i, \theta_{-i} \right) \eta_j^i \left( \hat{\theta}_i \right) \theta_i = E_{-i} \zeta_j^i \left( \hat{\theta}_i, \theta_{-i}, \vartheta \right) \frac{E_{-i} \omega_j^i \left( \hat{\theta}_i, \theta_{-i}, \vartheta \right) \zeta_j^i \left( \hat{\theta}_i, \theta_{-i}, \vartheta \right)}{E_{-i} \zeta_j^i \left( \hat{\theta}_i, \theta_{-i}, \vartheta \right)}$$

(B10)

$$= E_{-i} \omega_j^i \left( \hat{\theta}_i, \theta_{-i}, \vartheta \right) \zeta_j^i \left( \hat{\theta}_i, \theta_{-i}, \vartheta \right) \theta_i.$$

Trivially, $E_{-i} t_i (\theta_i) = t_i (\theta_i) = E_{-i} \tau (\theta)$, which combined with (B10) implies that the payoffs in (B8) and (B9) are identical. Since the equality between (B8) and (B9) were established for any $i$, $\theta_i$ and $\hat{\theta}_i$, it
follows that all incentive and participation constraints (IC) and (IR) hold for mechanism $G$ given that they are satisfied in mechanism $\mathcal{G}$. Moreover, [again by (B10)]

$$E_{-i} \left[ \sum_{j \in \mathcal{J}} \rho^j (\theta) \eta^j_i (\theta_i) \theta_i \right] = E_{-i} \left[ \sum_{j \in \mathcal{J}} \omega^j_i (\theta, \vartheta) \zeta^j_i (\theta, \vartheta) \theta_i \right],$$  

(B11)

so it follows by integration over $\Theta$ and summation over $i$ that

$$E \left[ \sum_{i \in \mathcal{I}} \sum_{j \in \mathcal{J}} \rho^j (\theta) \eta^j_i (\theta_i) \theta_i \right] = E \left[ \sum_{i \in \mathcal{I}} \sum_{j \in \mathcal{J}} \zeta^j_i (\theta, \vartheta) \omega^j_i (\theta, \vartheta) \theta_i \right],$$  

(B12)

By construction, we also have that $\rho^j (\theta) = E_{\mathcal{G}} \zeta^j (\theta, \vartheta)$ for every $\theta$. Thus $E \left[ \rho^j (\theta) C^j (n) \right] = E \left[ \zeta^j (\theta, \vartheta) C^j (n) \right]$, implying that

$$\sum_{j \in \mathcal{J}} E \rho^j (\theta) \left[ \sum_{i \in \mathcal{I}} \eta^j_i (\theta_i) \theta_i - C^j (n) \right] = \sum_{j \in \mathcal{J}} E \zeta^j (\theta, \vartheta) \left[ \sum_{i \in \mathcal{I}} \omega^j_i (\theta, \vartheta) \theta_i - C^j (n) \right].$$  

(B13)

Hence, $\mathcal{G}$ and $G$ generate the same social surplus.

**Claim B2** For every incentive feasible mechanism of the form (B6), there exists an anonymous simple incentive feasible mechanism $g$ of the form (B5) that generates the same surplus.

To see this, consider an incentive feasible simple mechanism $G$ on form (B6). For $k \in \{1, \ldots, n!\}$, let $P_k : \mathcal{I} \to \mathcal{I}$ denote the $k$-th permutation of the set of agents $\mathcal{I}$. Note that $P_k^{-1} (i)$ gives the index of the agent who takes agent $i$'s position in permutation $P_k$. Moreover, for any given $\theta \in \Theta^n$, let $\theta^{P_k} = (\theta_{P_k^{-1}(1)}, \ldots, \theta_{P_k^{-1}(n)}) \in \Theta^n$ denote the corresponding $k$-th permutation of $\theta$. For each $k \in \{1, \ldots, n!\}$, let $G_k = \left( (\rho^j_k, \eta^j_{k1}, \ldots, \eta^j_{kn})_{j=1,2}, t_{k1}, \ldots, t_{kn} \right)$ be given by

$$\rho^j_k (\theta) = \rho^j \left( \theta^{P_k} \right) \quad \forall \theta \in \Theta^n, j \in \mathcal{J},$$  

(B14)

$$\eta^j_{ki} (\theta_i) = \eta^j_{P_k^{-1}(i)} (\theta_i) \quad \forall \theta_i \in \Theta, j \in \mathcal{J}, i \in \mathcal{I},$$

$$t_{ki} (\theta_i) = t_{P_k^{-1}(i)} (\theta_i) \quad \forall \theta_i \in \Theta, i \in \mathcal{I},$$

and let $g = \left( (\rho^j, \eta^j_{1}, \ldots, \eta^j_{n})_{j=1,2}, \tilde{t}_{1}, \ldots, \tilde{t}_{n} \right)$ be given by

$$\tilde{\rho}^j (\theta) = \frac{1}{n!} \sum_{k=1}^{n!} \rho^j_k (\theta) \quad \forall \theta \in \Theta^n, j \in \mathcal{J},$$

$$\tilde{\eta}^j_{ki} (\theta_i) = \frac{1}{n!} \sum_{k=1}^{n!} E_{-i} \left[ \rho^j_k (\theta_i) \eta^j_{ki} (\theta_i) \right] \quad \forall \theta_i \in \Theta, i \in \mathcal{I}, j \in \mathcal{J},$$

$$\tilde{t}_{ki} (\theta_i) = \frac{1}{n!} \sum_{k=1}^{n!} t_{ki} (\theta_i) \quad \forall \theta_i \in \Theta, i \in \mathcal{I}.$$  

We now note that: (1) for each $j \in \mathcal{J}$, $\tilde{\rho}^j (\theta) = \tilde{\rho}^j (\theta')$ if $\theta'$ is a permutation of $\theta$. This is immediate since the sets $\{\rho^j_k (\theta)\}_{k=1}^{n!} = \{\rho^j (P_k (\theta))\}_{k=1}^{n!}$ and $\{\rho^j_k (\theta')\}_{k=1}^{n!} = \{\rho^j (P_k (\theta'))\}_{k=1}^{n!}$ are the same; (2) for $j \in \mathcal{J}$ and each pair $i, i' \in \mathcal{I}$, $\tilde{\eta}^j_{ki} (\cdot) = \tilde{\eta}^j_{ki'} (\cdot)$. That is, the inclusion rules are the same for all agents. To see this, consider agent $i$ and $i'$, and suppose that $\theta_i = \theta_{i'}$. We then have that $\left\{ E_{-i} \left[ \rho^j_k (\theta_i) \right] \eta^j_{ki} (\theta_i) \right\}_{k=1}^{n!}$ and $\left\{ E_{-i'} \left[ \rho^j_k (\theta_i') \right] \eta^j_{ki'} (\theta_{i'}) \right\}_{k=1}^{n!}$ are identical and that $E_{-i} \left[ \tilde{\rho}^j (\theta_i) \right] = E_{-i'} \left[ \tilde{\rho}^j (\theta_{i'}) \right]$; and (3) for each pair $i, i' \in \mathcal{I}$, $\tilde{t}_{ki} (\cdot) = \tilde{t}_{ki'} (\cdot)$, which is obvious since the sets $\{t_{ki} (\theta_i)\}_{k=1}^{n!}$ and $\{t_{ki} (\theta_i')\}_{k=1}^{n!}$ are identical. Together, (1), (2) and (3) establishes that $g$ is anonymous and simple.
Now we show that $g$ is incentive feasible and generates the same expected surplus as $G$. First, since $G$ and $G_k$ are identical except for the permutation of the agents, we have, for $k = 1, \ldots, n!$,

$$
\sum_{j \in J} E \left\{ \rho_k^j(\theta) \left[ \sum_{i \in I} \eta_{ki}^j(\theta_i) \theta_i^j - C^j(n) \right] \right\} = \sum_{j \in J} E \left\{ \rho^j(\theta) \left[ \sum_{i \in I} \eta_i^j(\theta_i) \theta_i^j - C^j(n) \right] \right\}.
$$

(B15)

Hence,

$$
\sum_{j \in J} E \left\{ \bar{\rho}^j(\theta) \left[ \sum_{i \in I} \eta_i^j(\theta_i) \theta_i^j - C^j(n) \right] \right\} = \sum_{j \in J} E \left\{ \frac{1}{n!} \sum_{k=1}^{n!} \rho_k^j(\theta) \left[ \sum_{i \in I} \frac{\sum_{k=1}^{n!} \rho_k^j(\theta) \eta_{ki}^j(\theta_i) \theta_i^j}{\sum_{k=1}^{n!} \rho_k^j(\theta)} - C^j(n) \right] \right\}
$$

$$
= \frac{1}{n!} \sum_{k=1}^{n!} \sum_{j \in J} E \left\{ \rho_k^j(\theta) \left[ \sum_{i \in I} \eta_{ki}^j(\theta_i) \theta_i^j - C^j(n) \right] \right\} = \sum_{j \in J} E \left\{ \rho^j(\theta) \left[ \sum_{i \in I} \eta_i^j(\theta_i) \theta_i^j - C^j(n) \right] \right\},
$$

where the last equality follows from (B15). Hence the surplus generated by $g$ is identical to that by original mechanism $G$. To show that $g$ is incentive feasible we first note that $E\rho_k^j(\theta) = E\rho^j(\theta)$ and $E \sum_{i \in I} t_{ki}(\theta_i) = E \sum_{i \in I} t_i(\theta_i)$ for all $k$, since the agents’ valuations are drawn from identical distributions and $G_k$ and $G$ only differ in the index of the agents. Thus

$$
E \sum_{i \in I} \tilde{t}_i(\theta_i) - \sum_{j \in J} E\rho^j(\theta) C^j(n) = E \sum_{i \in I} \frac{1}{n!} \sum_{k=1}^{n!} t_{ki}(\theta_i) - \sum_{j \in J} E \frac{1}{n!} \sum_{k=1}^{n!} \rho_k^j(\theta) C^j(n)
$$

$$
= E \sum_{i \in I} t_i(\theta_i) - \sum_{j \in J} E\rho^j(\theta) C^j(n),
$$

so $g$ satisfies (BB) if $G$ does. Second, (IC) holds for any permuted mechanism, that is,

$$
E_{-i} \sum_{j \in J} \rho_k^i(\theta) \eta_{ki}^j(\theta_i) \theta_i^j - t_{ki}(\theta_i) \geq E_{-i} \sum_{j \in J} \rho_k^i(\tilde{\theta}_i, \theta_{-i}) \eta_{ki}^j(\tilde{\theta}_i, \theta_{-i}) \theta_i^j - t_{ki}(\tilde{\theta}_i, \theta_{-i})
$$

(B16)

for all $i \in I$, and $\theta_i, \tilde{\theta}_i \in \Theta$. Hence,

$$
E_{-i} \sum_{j \in J} \bar{\rho}^j(\theta) \bar{\eta}^j(\theta_i) \theta_i^j - \bar{\tilde{t}}(\theta_i) = E_{-i} \sum_{j \in J} \left[ \frac{1}{n!} \sum_{k=1}^{n!} \rho_k^j(\theta) \right] \left[ \frac{\sum_{k=1}^{n!} \rho_k^j(\theta) \eta_{ki}^j(\theta_i) \theta_i^j}{\sum_{k=1}^{n!} \rho_k^j(\theta)} - \frac{1}{n!} \sum_{k=1}^{n!} t_{ki}(\theta_i) \right]
$$

$$
= \frac{1}{n!} \sum_{k=1}^{n!} \left[ E_{-i} \sum_{j \in J} \rho_k^j(\theta) \eta_{ki}^j(\theta_i) \theta_i^j - t_{ki}(\theta_i) \right] \geq \frac{1}{n!} \sum_{k=1}^{n!} \left[ E_{-i} \sum_{j \in J} \rho_k^j(\tilde{\theta}_i, \theta_{-i}) \eta_{ki}^j(\tilde{\theta}_i, \theta_{-i}) \theta_i^j - t_{ki}(\tilde{\theta}_i, \theta_{-i}) \right]
$$

$$
= E_{-i} \sum_{j \in J} \frac{1}{n!} \sum_{k=1}^{n!} \rho_k^j(\tilde{\theta}_i, \theta_{-i}) \eta_{ki}^j(\tilde{\theta}_i, \theta_{-i}) \theta_i^j - \frac{1}{n!} \sum_{k=1}^{n!} t_{ki}(\tilde{\theta}_i, \theta_{-i}) = \sum_{j \in J} E_{-i} \bar{\rho}^j(\tilde{\theta}_i, \theta_{-i}) \bar{\eta}^j(\tilde{\theta}_i) \theta_i^j - \frac{1}{n!} \sum_{k=1}^{n!} t_{ki}(\tilde{\theta}_i, \theta_{-i}) \tag{B17}
$$

where the inequality follows from (B16). Hence $g$ satisfies (IC). Finally, $g$ also satisfies the (IR) because (see the second line in (B17)) all the permuted mechanisms satisfy participation constraints. Proposition A.4 follows by combining Claims B1 and B2.

**PROOF OF PROPOSITION A.5:** This proof requires us to be explicit about the coordinates of the vector $\theta$ when permuting $J$. We therefore need some extra notation for this proof (only).

**Notation B1** We will, with some abuse of notation, write $F(\theta) = \Pi_{i \in I} F(\theta_i)$ and $F(\theta_{-i}) = \Pi_{k \in I \setminus i} F(\theta_k)$ as the joint distribution of $\theta$ and $\theta_{-i}$ respectively. We write $\theta_{i}^{-j} = \left( \theta_{i,1}^{1}, \ldots, \theta_{i,j}^{1}, \theta_{i,j+1}^{1}, \ldots, \theta_{i,n}^{1} \right)$ for a type
vector where good $j$ has been removed. Analogously, $\theta^{-j} = (\theta_{1}^{-j}, \ldots, \theta_{n}^{-j})$ stands for the type profile with good $j$ coordinate removed for all agents and $\theta^j = (\theta_{1}^{j}, \ldots, \theta_{n}^{j})$ is the vector collecting the valuations for good $j$ for all agents. Furthermore, $\theta_{-i}^{-j} = (\theta_{1}^{j}, \ldots, \theta_{i-1}^{j}, \theta_{i+1}^{j}, \ldots, \theta_{n}^{j})$ and $\theta_{-i}^{j} = (\theta_{1}^{j}, \ldots, \theta_{i-1}^{j}, \theta_{i+1}^{j}, \ldots, \theta_{n}^{j})$ are used for the vectors obtained respectively from $\theta^{-j}$ and $\theta^{j}$ by removing agent $i$. These conventions are used also on the distributions, so, for example, $\mathbf{F}_{-i}^{-j}$ denotes the cumulative distribution of $\theta_{-i}^{-j}$. Conditional distributions are denoted in the natural way: for example $\mathbf{F}_{-i}^{-j} (\cdot | \theta_{i}^{j})$ denotes the joint distribution of $\theta_{-i}^{-j}$ conditional on $\theta_{i}^{j}$. Since no integrals are taken over subsets of the range of integration, we also conserve space and write $\int_{\theta} h(\theta) d\mathbf{F}(\theta)$ rather than $\int_{\theta \in \Theta} h(\theta) d\mathbf{F}(\theta)$ when integrating a function $h$ over $\theta$ and similarly for integrals over various components of $\theta$.

Consider a simple anonymous incentive feasible mechanism $g$. For $k \in \{1, \ldots, M!\}$ let $P_{k} : \mathcal{J} \to \mathcal{J}$ be the $k$-th permutation of $\mathcal{J}$ and $\theta_{i}^{P_{k}} = (\theta_{1}^{P_{k}(1)}, \ldots, \theta_{n}^{P_{k}(M)}) \in \Theta$ be the permutation of $\theta$ when the goods are permuted according to $P_{k}$. Let $\theta^{P_{k}} = (\theta_{1}^{P_{k}}, \ldots, \theta_{n}^{P_{k}}) \in \Theta^{n}$ denote the corresponding permutation of $\theta$. For each $k \in \{1, \ldots, M!\}$ define mechanism $g_{k} = (\big\{ \rho_{k}^{j} \big\}_{j \in \mathcal{J}}, \big\{ \eta_{k}^{j} \big\}_{j \in \mathcal{J}}, t_{k})$, where for every $\theta \in \Theta^{n}$;

1. $\rho_{k}^{j} (\theta) = \rho_{k}^{P_{k}^{-1}(j)} (\theta_{i}^{P_{k}})$ for every $j \in \mathcal{J}$;  
2. $\eta_{k}^{j} (\theta_{i}) = \eta_{k}^{P_{k}^{-1}(j)} (\theta_{i}^{P_{k}})$ for every $j \in \mathcal{J}$;  
3. $t_{k} (\theta_{i}) = t_{i} (\theta_{i}^{P_{k}})$.

By construction, each $g_{k}$ is simple. Each $g_{k}$ is also anonymous by the anonymity of $g$. Using the definition of $g_{k}$ and manipulating the result by observing that the labeling of the variables is irrelevant, we get:

\[
\begin{aligned}
\mathcal{E} \rho_{k}^{j} (\theta) \eta_{k}^{j} (\theta_{i}) \theta_{i}^{j} &= \int_{\theta} \rho_{k}^{j} (\theta) \eta_{k}^{j} (\theta_{i}) \mathbf{F}(\theta) / \text{def of } g_{k} / = \int_{\theta \in \Theta^{n}} \rho_{k}^{P_{k}^{-1}(j)} (\theta_{i}^{P_{k}}) \eta_{k}^{P_{k}^{-1}(j)} (\theta_{i}^{P_{k}}) \theta_{i}^{j} d\mathbf{F}(\theta) \\
&= \int_{\theta^{j}} \left[ \int_{\theta^{-j}} \rho_{k}^{P_{k}^{-1}(j)} (\theta_{i}^{P_{k}}) \eta_{k}^{P_{k}^{-1}(j)} (\theta_{i}^{P_{k}}) \theta_{i}^{j} d\mathbf{F}^{-j} (\theta^{-j} | \theta^{j}) \right] d\mathbf{F}^{j} (\theta^{j}) \quad \text{(B18)} \quad \\
&= \int_{\theta^{P_{k}^{-1}(j)}} \left[ \int_{(\theta^{-j})} \rho_{k}^{P_{k}^{-1}(j)} (\theta) \eta_{k}^{P_{k}^{-1}(j)} (\theta_{i}) \theta_{i}^{P_{k}^{-1}(j)} d\mathbf{F}^{-j} \left( \theta^{-j} \bigg| \text{ j-th argument } \right) \right] d\mathbf{F}^{j} (\theta^{P_{k}^{-1}(j)}) \quad \\
\end{aligned}
\]

where we recall,

\[
(\theta^{-j})^{P_{k}} = (\theta_{P_{k}^{-1}(1)}, \ldots, \theta_{P_{k}^{-1}(j-1)}, \theta_{P_{k}^{-1}(j+1)}, \ldots, \theta_{P_{k}^{-1}(n)}) \quad \text{(B19)}
\]

---

\textsuperscript{9}To illustrate, suppose $n = 2$, $M = 3$, and $\theta = (\theta_{1}, \theta_{2}) = ((1, 2, 0), (3, 2, 1))$. Consider, for example, permutation $k$ given by $P_{k} (1) = 2$, $P_{k} (2) = 1$, $P_{k} (3) = 3$. Then $P_{k}^{-1}(1) = 2$, $P_{k}^{-1}(2) = 1$, $P_{k}^{-1}(3) = 3$ and $\theta_{i}^{P_{k}} = (\theta_{1}^{P_{k}^{-1}(1)}, \theta_{2}^{P_{k}^{-1}(2)}, \theta_{3}^{P_{k}^{-1}(3)}) = (2, 1, 0), \theta_{2}^{P_{k}} = (\theta_{2}^{P_{k}^{-1}(1)}, \theta_{2}^{P_{k}^{-1}(2)}, \theta_{2}^{P_{k}^{-1}(3)}) = (2, 3, 1), \theta_{3}^{P_{k}} = (\theta_{3}^{P_{k}}, \theta_{3}^{P_{k}}) = ((2, 1, 0), (2, 3, 1)).$

\textsuperscript{9}This implies that $\rho_{P_{k}^{-1}(j)} (\theta_{i}^{P_{k}}) = \rho (\theta)$ for every $j \in \mathcal{J}$.

\textsuperscript{10}This implies that $\eta_{P_{k}^{-1}(j)} (\theta_{i}^{P_{k}}) = \eta (\theta_{i})$ for every $j \in \mathcal{J}$.

\textsuperscript{11}It is important to point out that, in reaching the fourth equality in (B18), we can relabel the integrating variables (since they are dummies) but not the integrating functions.
By exchangeability, we have

\[ dF^{-j} \left( (\theta^{-j})^{P_k} \left| \begin{array}{c} \theta_{P_k}^{-1}(j) \\ j\text{-th (vector) argument} \end{array} \right. \right) \]

(B20)

\[ = dF^{-j} \left( \theta_{P_k}^{-1}(1), ..., \theta_{P_k}^{-1}(j-1), \theta_{P_k}^{-1}(j+1), ..., \theta_{P_k}^{-1}(n) \right| j\text{-th (vector) argument} = \theta_{P_k}^{-1}(j) \right) \]

\[ = dF^{-j} \left( \theta^{-j} | j\text{-th (vector) argument} = \theta_{P_k}^{-1}(j) \right) \]

\[ = dF^{-P_k^{-1}(j)} \left( \theta_{P_k}^{-1}(j) | P_k^{-1}(j) \text{-th (vector) argument} = \theta_{P_k}^{-1}(j) \right) ; \]

and

\[ dF^j \left( \theta_{P_k}^{-1}(j) \right) = dF^{\theta_{P_k}^{-1}(j)} \left( \theta_{P_k}^{-1}(j) \right). \] (B21)

Using (B18), (B20) and (B21), we have that

\[
\begin{align*}
E_{\rho_k^j} (\theta) \eta_{k}^j (\theta_i) \theta_i^j & \\
= \int_{\theta_{P_k}^{-1}(j)} \left[ \int_{(\theta^{-j})^{P_k}} \rho_{k}^{P_k^{-1}(j)} (\theta) \eta_{k}^{P_k^{-1}(j)} (\theta_i) \theta_{P_k}^{P_k^{-1}(j)} \right] dF^{-j} \left( (\theta^{-j})^{P_k} \left| \begin{array}{c} \theta_{P_k}^{-1}(j) \\ j\text{-th (vector) argument} \end{array} \right. \right) \right] dF^j \left( \theta_{P_k}^{-1}(j) \right) \\
= \int_{\theta_{P_k}^{-1}(j)} \left[ \int_{(\theta^{-j})^{P_k}} \rho_{k}^{P_k^{-1}(j)} (\theta) \eta_{k}^{P_k^{-1}(j)} (\theta_i) \theta_{P_k}^{P_k^{-1}(j)} \right] dF^{-P_k^{-1}(j)} \left( \theta^{-P_k^{-1}(j)} \left| \begin{array}{c} \theta_{P_k}^{-1}(j) \\ \theta_{P_k}^{-1}(j) \end{array} \right. \right) \right] dF^{P_k^{-1}(j)} \left( \theta_{P_k}^{-1}(j) \right) \\
= \int_{\theta_{P_k}^{-1}(j)} \rho_{k}^{P_k^{-1}(j)} (\theta) \eta_{k}^{P_k^{-1}(j)} (\theta_i) \theta_{P_k}^{P_k^{-1}(j)} \right) dF (\theta) = E_{\rho_k^j} (\theta) \eta_{k}^{P_k^{-1}(j)} (\theta_i) \theta_{P_k}^{P_k^{-1}(j)}.
\end{align*}
\]

Moreover, exchangeability implies that \( Et_k (\theta_i) = Et \left( \theta_i^{P_k} \right) = Et (\theta_i) \). The ex ante utility,

\[ E \left[ \sum_{j=1}^{M} \rho_{k}^{j} (\theta) \eta_{k}^{j} (\theta_i) \theta_{i}^{j} - t_k (\theta_i) \right] \]

\[ = \left[ \sum_{j=1}^{M} E \rho_{k}^{P_k^{-1}(j)} (\theta) \eta_{k}^{P_k^{-1}(j)} (\theta_i) \theta_{P_k}^{P_k^{-1}(j)} \right] - Et (\theta_i) \]

\[ = \left[ \sum_{j=1}^{M} E \rho^{j} (\theta) \eta^{j} (\theta_i) \theta_{i}^{j} \right] - Et (\theta_i), \] (B23)

is thus unchanged when changing from \( g \) to \( g_k \). The same steps as in (B18) through (B22) (only somewhat simpler) establishes that \( E_{\rho_k^j} (\theta) = E \rho_{k}^{P_k^{-1}(j)} \) for every \( j \), implying that

\[
\begin{align*}
E \left[ \sum_{j=1}^{M} \rho_{k}^{j} (\theta) C^{j} (n) - \sum_{i} t_k (\theta_i) \right] & = \left[ C (n) E \sum_{j=1}^{M} \rho_{k}^{j} (\theta) - \sum_{i} Et_k (\theta_i) \right] \]

(B24)

\[ = \left[ C (n) E \sum_{j=1}^{M} \rho^{j} (\theta) - \sum_{i} Et (\theta_i) \right] \]

so the feasibility constraint is unaffected when changing from \( g \) to \( g_k \). Next, write \( U(\theta_i, \theta_i' ; g) \) and \( U(\theta_i, \theta_i' ; g_k) \) for the expected utility from announcing \( \theta_i' \) when the true type is \( \theta_i \) in mechanisms \( g \) and \( g_k \) respectively. Next, by a calculation in the same spirit as (B18) through (B22):
\[ E_{-i} \rho_k^j (\theta_i, \theta_i') = \int_{\theta_i} \rho_k^j (\theta_i, \theta_i') dF_{-i} (\theta_i) / \text{def of } g_k / = \int_{\theta_i} \rho_k^{P_k^{-1}(j)} (\theta_i, \theta_i') dF_{-i} (\theta_i) \]

\[ = \int_{\theta_i} \left[ \int_{\theta_i} \rho_k^{P_k^{-1}(j)} (\theta_i, \theta_i') dF_{-i} (\theta_i) \right] dF_{-i} (\theta_i') \]

\[ \text{/relabel/} = \int_{\theta_i} \rho_k^{P_k^{-1}(j)} (\theta_i, \theta_i') dF_{-i} (\theta_i) \]

\[ \text{/exchangeability/} = \int_{\theta_i} \rho_k^{P_k^{-1}(j)} (\theta_i, \theta_i') dF_{-i} (\theta_i) = E_{-i} \rho_k^{P_k^{-1}(j)} (\theta_i, \theta_i') \]

That is, the perceived probability of getting \( j \) when announcing \( \theta_i' \) in mechanism \( g_k \) is the same as the perceived probability of getting good \( P_k^{-1}(j) \) when announcing \( (\theta_i')_k \), so that

\[ U(\theta_i, \theta_i'; g_k) = E_{-i} \sum_{j=1}^M \rho_k^j (\theta_i, \theta_i') \eta_k^j (\theta_i') \theta_i E_{-i} \rho_k^{P_k^{-1}(j)} (\theta_i, \theta_i') - t (\theta_i') \]

\[ \text{B26} \]

whereas

\[ U(\theta_i, \theta_i'; g) = \sum_{j=1}^M \eta_k^j (\theta_i') \theta_i E_{-i} \rho_k^j (\theta_i, \theta_i') - t (\theta_i') \]

\[ \text{B27} \]

which establishes that type \( \theta_i \) who announces \( \theta_i' \) in mechanism \( g_k \) gets the same utility as type \( \theta_i' \) who announces \( (\theta_i')_k \) in mechanism \( g \). Hence incentive compatibility and individual rationality of \( g_k \) follows from incentive compatibility and individual rationality of \( g \). Now, construct a new mechanism \( \tilde{g} = \{ \tilde{\rho}_j \}_{j \in J}, \{ \tilde{\eta}_j \}_{j \in J}, \tilde{t} \) by letting

\[ \tilde{\rho}_j (\theta) = \frac{1}{\lambda} \sum_{k=1}^{M_1} \rho_k^j (\theta) \]

\[ \tilde{\eta}_j (\theta_i) = \frac{\sum_{k=1}^{M_1} \eta_k^j (\theta_i) E_{-i} \rho_k^j (\theta)}{\sum_{k=1}^{M_1} E_{-i} \rho_k^j (\theta)} \]

\[ \tilde{t} (\theta_i) = \frac{1}{\lambda} \sum_{k=1}^{M_1} t (\theta_i') \]

let \( P : J \to J \) be an arbitrary perturbation of the set of goods. Then,

\[ \tilde{\rho}_k^{P_k^{-1}(j)} (\theta^P) = \frac{1}{\lambda} \sum_{k=1}^{M_1} \rho_k^{P_k^{-1}(j)} (\theta^P) \]

\[ \text{B29} \]

since the sets \( \{ \rho_k^{P_k^{-1}(j)} (\theta^P) \}_{k=1}^{M_1} \) and \( \{ \rho_k^{P_k^{-1}(j)} (\theta^P) \}_{k=1}^{M_1} \) are identical. Furthermore

\[ \tilde{\eta}_k^{P_k^{-1}(j)} (\theta^P) = \frac{\sum_{k=1}^{M_1} \eta_k^{P_k^{-1}(j)} (\theta^P) E_{-i} \rho_k^{P_k^{-1}(j)} (\theta^P)}{\sum_{k=1}^{M_1} E_{-i} \rho_k^{P_k^{-1}(j)} (\theta^P)} \]

\[ \text{B30} \]
for the same reason. It is obvious that \( \tilde{t}(\theta_i') = \tilde{t}(\theta_i) \), which together with (B29) and (B30) establishes that \( g \) is symmetric. To complete the proof we need to show that \( g \) is incentive feasible and generates the same surplus as \( g \). We note that

\[
E \rho^j_i(\theta) \eta^j_i(\theta_i) \theta_i^j = \frac{1}{M} \sum_{k=1}^M E \rho^j_k(\theta) \frac{\sum_{k=1}^M \eta^j_k(\theta_i) E_{-\rho^j_k}(\theta) \eta^j_i}{\sum_{k=1}^M E_{-\rho^j_k}(\theta)} \theta_i^j
\]

\[
= \frac{1}{M} E \theta_i \sum_{k=1}^M \left[ E_{-\rho^j_k}(\theta) \frac{\sum_{k=1}^M \eta^j_k(\theta_i) E_{-\rho^j_k}(\theta) \eta^j_i}{\sum_{k=1}^M E_{-\rho^j_k}(\theta)} \right] = \frac{1}{M} E \left[ \sum_{k=1}^M \eta^j_k(\theta_i) \rho^j_k(\theta) \theta_i^j - t_k(\theta_i) \right]
\]

\[
= E \left[ \sum_{j=1}^M \eta^j_i(\theta_i) \rho^j (\theta) \theta_i^j - t(\theta_i) \right],
\]

where the last equality follows from (B22) and (B23), which establishes that the ex ante utility from \( g \) and \( g \) are the same for all agents. Moreover,

\[
E \left[ \sum_{j=1}^M \tilde{\rho}^j_i(\theta_i) C^j(n) - \sum_{i=1}^n \tilde{t}(\theta_i) \right] = E \left[ \sum_{j=1}^M \rho^j_i(\theta) C^j(n) - \sum_{i=1}^n t(\theta_i) \right] = E \left[ \sum_{j=1}^M \rho^j (\theta) C^j(n) - \sum_{i=1}^n t(\theta_i) \right],
\]

where the third equality follows from (B24). So the budget balance constraint is unaffected. All incentive compatibility constraints hold since,

\[
U(\theta_i; \theta_i'; g) = \sum_{j=1}^M \eta^j_i(\theta_i') \eta^j_i(\theta_i) \rho^j_i(\theta_i) \theta_i^j - \tilde{t}(\theta_i')
\]

\[
= \frac{1}{M} \sum_{k=1}^M \eta^j_k(\theta_i') E_{-\rho^j_k}(\theta) \rho^j_i(\theta_i) \theta_i^j - t_k(\theta_i')
\]

\[
= \frac{1}{M} \sum_{k=1}^M \eta^j_k(\theta_i') E_{-\rho^j_k}(\theta) \rho^j_i(\theta_i) \theta_i^j - \frac{1}{M} \sum_{k=1}^M t_k(\theta_i')
\]

\[
= \frac{1}{M} \sum_{k=1}^M U(\theta_i; \theta_i'; g_k) \leq \frac{1}{M} \sum_{k=1}^M U(\theta; g_k) = U(\theta; g).
\]

where the third equality follows from (B26). By the same calculation, \( U(\theta; g) = \frac{1}{M} \sum_{k=1}^M U(\theta; g_k) \geq 0 \), since all participation constraints hold for each \( k \). This completes the proof.

\[ \square \]

### B Other Omitted Proofs

**PROOF OF THE EXISTENCE OF SOLUTION TO PROBLEM (9) IN SECTION 3.1:** The only variables that are not automatically in a compact set are the transfers. However, \( t_i(1) \leq Ml < Mh \) and \( t_i(\theta_i) - t_i(\theta_i|l_k) \leq m(\theta_i) h + [M - m(\theta_i)] l < Mh \). Recursive application of (10) therefore implies that we may bound \( t_i(\theta_i) \) from above by \( M^2h \). Since this is also an upper bound for the difference between \( t_i(\theta_i) \) and \( t_i(\theta_i|l_k) \), it follows from (5) that we may bound \( t_i(\theta_i) \) from below by \(-M^2h \). Hence, existence of a solution to (9) follows from Weierstrass maximum theorem.

\[ \square \]

**PROOF OF LEMMA 1:** Let \( m(\theta_i) = m(\tilde{\theta}_i) = \tilde{m} \), let \( \lambda_i(\theta_i; \theta_i') \) denote the multiplier associated with one of the \( m - 1 \) downwards adjacent constraints for type \( \theta_i \) and let \( \lambda_i(\tilde{\theta}_i; \tilde{\theta}_i') \) denote the multiplier associated with one of the \( m - 1 \) downwards adjacent constraints for type \( \tilde{\theta}_i \). Proposition A.5 ensures
that provision and inclusion rules are symmetric and by use of strong duality in linear programming we
find that it is without loss to assume that \( \lambda_i (\theta_i, \theta_i^j) = \lambda_i (\tilde{\theta}_i, \tilde{\theta}_i^j) \).

**PROOF OF LEMMA 2:** Fix \( m \) and let \( \theta_i \in \Theta \) with \( m (\theta_i) = m \{1, ..., M - 1\} \). Consider the incentive
constraints that involves \( \theta_i \):

\[
0 \leq \sum_{\theta_{-i}} \beta_{-i} (\theta_{-i}) \sum_{j=1}^M \rho^j (\theta) \eta_i^j (\theta_i) \theta_i^j - t_i (\theta_i) - \sum_{\theta_{-i}} \beta_{-i} (\theta_{-i}) \sum_{j=1}^M \rho^j (\theta_{-i}, \theta_i | l_k) \eta_i^j (\theta_i | l_k) \theta_i^j - t_i (\theta_i | l_k)
\]

\( (B31) \)

There are \( m \) different adjacent downward deviations from \( \theta_i \) (i.e. to replace a single high-value
coordinate in \( \theta_i \) with a low-value); thus \( t_i (\theta_i) \) enters in Term A for \( m \) conditions. From Lemma 1, the
multiplier associated with each of these conditions is \( \lambda (m) \). Moreover, there are \( M - m \) types of \( \theta_i^j \) with
\( m (\theta_i^j) = m + 1 \) such that an adjacent downward deviation from \( \theta_i^j \) can “turn into” type \( \theta_i^j \); thus \( t_i (\theta_i) \)
enters in Term B for \( M - m \) downwards incentive constraints for types with \( m + 1 \) high valuations.
Again from Lemma 1, the multiplier associated with each of these conditions is \( \lambda (m + 1) \). Finally, \( t_i (\theta_i) \)
appears in the balanced budget constraint (5). The first order condition with respect to \( t_i (\theta_i) \) can thus
be written as

\[
-m \lambda (m) + (M - m) \lambda (m + 1) + \Lambda \beta_i (\theta_i) = 0,
\]

\( (B32) \)

where we used (12) for the first equality.

When \( m (\theta_i) = 0 \), i.e. when \( \theta_i = 1 = (1, ..., 1) \), there is no adjacent downward deviation from \( \theta_i \); instead,
\( t_i (1) \) appears in the individual rationality constraint (4) for type-I. Thus the optimality condition with
respect to \( t_i (1) \) is:

\[-\lambda (0) + \lambda (1) M + \Lambda \beta_i (1) = 0.\]

Similarly, the optimality condition with respect to \( t_i (h) \) where \( h = (h, ...., h) \) is

\[-M \lambda (M) + \Lambda \beta_i (h) = 0.\]

For \( m = M \), condition (B32) reads \( M \lambda (M) = \Lambda \beta_M \), implying that Lemma 2 is also true for \( m = M \).
Now suppose that \( \lambda (m) \) is given by the expression in (13) for some \( m \leq M \). The optimality condition
(B32) with respect to \( t_i (\theta_i^j) \) where \( m (\theta_i^j) = m - 1 \) then reads:

\[
0 = -(m - 1) \lambda (m - 1) + (M - m + 1) \lambda (m) + \frac{(m - 1)! (M - m + 1)!}{M!} \beta_{m-1}
\]

\[
= -(m - 1) \lambda (m - 1) + \frac{(M - m + 1)}{m} m \lambda (m) + \frac{(m - 1)! (M - m + 1)!}{M!} \beta_{m-1}
\]

\[
= -(m - 1) \lambda (m - 1) + \frac{(M - m + 1) M! (M - m)!}{M!} \Lambda \sum_{j=m}^M \beta_j + \frac{(m - 1)! (M - m + 1)!}{M!} \beta_{m-1}
\]

\[
= -(m - 1) \lambda (m - 1) + \frac{(m - 1)! (M - m + 1)!}{M!} \Lambda \sum_{j=m-1}^M \beta_j,
\]

where the third equality follows from induction hypothesis. Thus, (13) holds also for \( m - 1 \). The result
follows from induction. ■
PROOF OF PROPOSITION 1: This follows from the following two lemmas: Lemma B1 and Lemma B2.

Lemma B1 (Relations Among Various Incentive Constraints)

1. If the downward adjacent constraints in (9) **bind** at \((\rho, \eta, t)\), then all upward adjacent incentive constraints in (6) are satisfied.

2. If \((\rho, \eta, t)\) is monotonic and that all downward (upward, respectively) adjacent incentive constraints hold, then all downward (upward, respectively) constraints in (6) are satisfied.

3. If \((\rho, \eta, t)\) is monotonic and that all downward and upward incentive constraints hold, then all incentive constraints in (6) are satisfied.

**PROOF:** [Part 1] Consider types \(\theta_i\) and \(\theta'_i\) with \(m(\theta_i) = m\) and \(m(\theta'_i) = m + 1\). For ease of notation, define \(U(m, m)\) and \(U(m + 1, m + 1)\) as the payoff of truth-telling for type \(m\) and \(m + 1\); and denote the payoff from a type with \(m + 1\) high valuations to announce a type with \(m\) high valuations as \(U(m + 1, m)\), and the payoff from a type with \(m\) high valuations to announce \(m + 1\) high valuations as \(U(m + 1, m)\). \(U(m + 1, m)\) and \(U(m, m + 1)\) are respectively given as:

\[
U(m + 1, m) = \sum_{\theta_i \in \Theta_i} \beta_{-i}(\theta_{-i}) \left\{ P^h(\theta_{-i}, m) mh + P^l(\theta_{-i}, m) \eta(m) (M - m - 1) l + h \right\} - t(m),
\]

\[
U(m, m + 1) = \sum_{\theta_i \in \Theta_i} \beta_{-i}(\theta_{-i}) \left[ P^h(\theta_{-i}, m + 1) mh + P^l(\theta_{-i}, m + 1) \eta(m + 1) (M - m - 1) l \right] - t(m + 1).
\]

We then have that

\[
\begin{align*}
U(m, m) - U(m + 1, m) &= \sum_{\theta_i \in \Theta_i} \beta_{-i}(\theta_{-i}) P^h(\theta_{-i}, m) mh + P^l(\theta_{-i}, m) \eta(m) (M - m - 1) l - t(m) \\
&- \sum_{\theta_i \in \Theta_i} \beta_{-i}(\theta_{-i}) \left[ P^h(\theta_{-i}, m, m + 1) [mh + l] + P^l(\theta_{-i}, m + 1) \eta(m + 1) (M - m - 1) l \right] - t(m + 1) \\
&= \sum_{\theta_i \in \Theta_i} \beta_{-i}(\theta_{-i}) P^h(\theta_{-i}, m) mh + P^l(\theta_{-i}, m) \eta(m) \{(M - m - 1) l + h\} - t(m) \\
&= \sum_{\theta_i \in \Theta_i} \beta_{-i}(\theta_{-i}) P^h(\theta_{-i}, m) mh + P^l(\theta_{-i}, m) \eta(m) \{(M - m - 1) l + h\} - t(m) \\
&= U(m + 1, m) \tag{= by hypothesis}
\end{align*}
\]

\[
\begin{align*}
&+ \sum_{\theta_i \in \Theta_i} \beta_{-i}(\theta_{-i}) \left[ P^h(\theta_{-i}, m + 1) [mh + l] + P^l(\theta_{-i}, m + 1) \eta(m + 1) (M - m - 1) l \right] - t(m + 1) \\
&+ \sum_{\theta_i \in \Theta_i} \beta_{-i}(\theta_{-i}) \left[ P^h(\theta_{-i}, m + 1) [mh + l] + P^l(\theta_{-i}, m + 1) \eta(m + 1) (M - m - 1) l \right] - t(m + 1) \\
&\geq U(m + 1, m + 1) \tag{\geq 0 as \(P^h(\theta_{-i}, m + 1) - P^l(\theta_{-i}, m) \eta(m) \geq 0\)}
\end{align*}
\]

\[
\begin{align*}
&\geq 0. 
\end{align*}
\]
[Part 2] [Downward Incentive Constraints] The proof is by induction. Pick an arbitrary $m$. Assume that there is some $K < m$ such that a type with $m$ high valuations has no incentives to pretend to be of any type with $k \in \{m - 1, \ldots, K\}$ high valuations. It follows that

\[
U(m, m) = \sum_{\theta_{-i} \in \Theta_{-i}} \beta_{-i}(\theta_{-i}) \left[ P^h(\theta_{-i}, m) mh + P^l(\theta_{-i}, m) \eta(m)(M - m)l \right] - t(m)
\]

\[
\geq \sum_{\theta_{-i} \in \Theta_{-i}} \beta_{-i}(\theta_{-i}) \left[ P^h(\theta_{-i}, K) K h + P^l(\theta_{-i}, K) \eta(K)(M - m)l + (m - K) h \right] - t(K)
\]

\[
= U(m, K)
\]

is satisfied by hypothesis. By assumption the downwards adjacent incentive constraint for type $K$ holds, implying that

\[
U(K, K) = \sum_{\theta_{-i} \in \Theta_{-i}} \beta_{-i}(\theta_{-i}) \left[ P^h(\theta_{-i}, K) K h + P^l(\theta_{-i}, K) \eta(K)(M - K)l \right] - t(K)
\]

\[
\geq \sum_{\theta_{-i} \in \Theta_{-i}} \beta_{-i}(\theta_{-i}) \left[ P^h(\theta_{-i}, K - 1) (K - 1) h + P^l(\theta_{-i}, K - 1) \eta(K - 1)(M - K)l + h \right] - t(K - 1)
\]

\[
= U(K, K - 1)
\]

But, the payoff of announcing type $K - 1$ for type $m$ is

\[
\sum_{\theta_{-i} \in \Theta_{-i}} \beta_{-i}(\theta_{-i}) \left[ P^h(\theta_{-i}, K - 1) (K - 1) h + P^l(\theta_{-i}, K) \eta(K - 1)(M - m)l + (m - K + 1) h \right] - t(K - 1)
\]

\[
= \sum_{\theta_{-i} \in \Theta_{-i}} \beta_{-i}(\theta_{-i}) \left[ P^h(\theta_{-i}, K - 1) (K - 1) h + P^l(\theta_{-i}, K) \eta(K - 1)(M - K)l + h \right] - t(K - 1)
\]

\[
+ \sum_{\theta_{-i} \in \Theta_{-i}} \beta_{-i}(\theta_{-i}) P^l(\theta_{-i}, K - 1) \eta(K - 1)(m - K)(h - l)
\]

\[
/\text{B34}/ \leq \sum_{\theta_{-i} \in \Theta_{-i}} \beta_{-i}(\theta_{-i}) \left[ P^h(\theta_{-i}, K) K h + P^l(\theta_{-i}, K) \eta(K)(M - K)l \right] - t(K)
\]

\[
+ \sum_{\theta_{-i} \in \Theta_{-i}} \beta_{-i}(\theta_{-i}) P^l(\theta_{-i}, K - 1) \eta(K - 1)(m - K)(h - l)
\]

\[
= \sum_{\theta_{-i} \in \Theta_{-i}} \beta_{-i}(\theta_{-i}) \left[ P^h(\theta_{-i}, K) K h + P^l(\theta_{-i}, K) \eta(K)(M - m)l + (m - K) h \right] - t(K)
\]

\[
- \sum_{\theta_{-i} \in \Theta_{-i}} \beta_{-i}(\theta_{-i}) P^l(\theta_{-i}, K) \eta(K)(m - K)(h - l)
\]

\[
+ \sum_{\theta_{-i} \in \Theta_{-i}} \beta_{-i}(\theta_{-i}) P^l(\theta_{-i}, K - 1) \eta(K - 1)(m - K)(h - l)
\]

\[
/\text{B33} \text{ and } P^l(\theta_{-i}, K - 1) \eta(K - 1) \leq P^l(\theta_{-i}, K) \eta(K) \]

\[
\leq \sum_{\theta_{-i} \in \Theta_{-i}} \beta_{-i}(\theta_{-i}) \left[ P^h(\theta_{-i}, m) mh + P^l(\theta_{-i}, m) \eta(m)(M - m)l \right] - t(m),
\]

implying that $m$ has no incentive to mimic $K - 1$. By induction it follows that all downwards constraints are satisfied.
[Upward Incentive Constraints] The proof is by induction. Let $K > m$ and assume that

$$U (m, m) = \sum_{\theta_{-i} \in \Theta_{-i}} \beta_{-i} (\theta_{-i}) \left\{ P^h (\theta_{-i}, m) mh + P^l (\theta_{-i}, m) \eta (m) (M - m) l \right\} - t (m)$$

$$\geq \sum_{\theta_{-i} \in \Theta_{-i}} \beta_{-i} (\theta_{-i}) \left\{ P^h (\theta_{-i}, k) [mh + (k - m) l] + P^l (\theta_{-i}, k) \eta (k) (M - k) l \right\} - t (k)$$

$$= U (m, k)$$

for all $k \in \{m + 1, \ldots, K\}$. If $K = M$, all upwards constraint hold by assumption. If $K < M$, the upwards adjacent constraint for type $K$ implies that

$$U (K, K) = \sum_{\theta_{-i} \in \Theta_{-i}} \beta_{-i} (\theta_{-i}) P^h (\theta_{-i}, K) K h + P^l (\theta_{-i}, K) \eta (K) (M - K) l - t (K)$$

$$\geq \sum_{\theta_{-i} \in \Theta_{-i}} \beta_{-i} (\theta_{-i}) P^h (\theta_{-i}, K + 1) [K h + l] + P^l (\theta_{-i}, K + 1) \eta (K + 1) (M - K - 1) l - t (K + 1)$$

$$= U (K, K + 1).$$

We then note that

$$U (m, m) - U (m, K + 1) \geq U (m, K) - U (m, K + 1)$$

$$= \sum_{\theta_{-i} \in \Theta_{-i}} \beta_{-i} (\theta_{-i}) \left\{ P^h (\theta_{-i}, K) [mh + (K - m) l] + P^l (\theta_{-i}, K) \eta (K) (M - K) l \right\} - t (K)$$

$$- \sum_{\theta_{-i} \in \Theta_{-i}} \beta_{-i} (\theta_{-i}) P^h (\theta_{-i}, K + 1) [mh + (K + 1 - m) l] + P^l (\theta_{-i}, K + 1) \eta (K + 1) (M - K - 1) l - t (K + 1)$$

$$= \sum_{\theta_{-i} \in \Theta_{-i}} \beta_{-i} (\theta_{-i}) \left\{ P^h (\theta_{-i}, K) K h + P^l (\theta_{-i}, K) \eta (K) (M - K) l \right\} - t (K)$$

$$+ \sum_{\theta_{-i} \in \Theta_{-i}} \beta_{-i} (\theta_{-i}) \left\{ P^h (\theta_{-i}, K) (K - m) (l - h) \right\}$$

$$- \sum_{\theta_{-i} \in \Theta_{-i}} \beta_{-i} (\theta_{-i}) P^h (\theta_{-i}, K + 1) [K h + l] + P^l (\theta_{-i}, K + 1) \eta (K + 1) (M - K - 1) l - t (K + 1)$$

$$+ \sum_{\theta_{-i} \in \Theta_{-i}} \beta_{-i} (\theta_{-i}) P^h (\theta_{-i}, K + 1) (K - m) (h - l)$$

$$= U (K, K) - U (K, K + 1) + \sum_{\theta_{-i} \in \Theta_{-i}} \beta_{-i} (\theta_{-i}) \left[ P^h (\theta_{-i}, K + 1) - P^h (\theta_{-i}, K) \right] (K - m) (h - l),$$

$$\geq 0 \text{ by (B35)}$$

$$\geq 0 \text{ by monotonicity of } P^h$$

implying that type $m$ has no incentive to mis-report as type $K + 1$.

[Part 3] The solution to (9) violates an incentive constraint in (6) if there exists $\theta_i, \theta_i'$ such that

$$\sum_{\theta_{-i} \in \Theta_{-i}} \beta_{-i} (\theta_{-i}) \sum_{j=1}^{M} \rho^j (\theta_i) \eta_i^j (\theta_i) \theta_i^j - t_i (\theta_i) < \sum_{\theta_{-i} \in \Theta_{-i}} \beta_{-i} (\theta_{-i}) \sum_{j=1}^{M} \rho^j (\theta_{-i}, \theta_i') \eta_i^j (\theta_i') \theta_i^j - t_i (\theta_i').$$

(B36)

Since $\theta_i$ is exchangeable and costs are identical for all goods, we can apply Proposition A.5 (in conjunction with Lemma 3) to conclude that it is without loss of generality to assume that there exists $\{\eta (m), P^h (\theta_{-i}, m), P^l (\theta_{-i}, m), t (m)\}_{m=0}^{M}$, such that:

- $\eta_i^j (\theta_i) = \eta (m)$ for every $(\theta_i, j)$ such that $\theta_i^j = l$ for good $j$ and $m (\theta_i) = m$;
- $\rho^j (\theta_{-i}, \theta_i') = P^h (\theta_{-i}, m)$ for every $(\theta_i, j)$ such that $\theta_i^j = h$ for good $j$ and $m (\theta_i) = k$;
• \( \rho^j (\theta_{-i}, \theta^j_i = P^j (\theta_{-i}, m) \) for every \((\theta_{-i}, j)\) such that \( \theta^j_i = l \) for good \( j \) and \( m(\theta_i) = k \);

• \( t_i (\theta_i) = t(m) \) for every \( \theta_i \) such that \( \theta^k_i = h \) and \( m(\theta_i) = k \).

Consider an arbitrary announcement \( \theta^j_i \) with \( m(\theta^j_i) = m^\prime \). Let \( r \leq \min \{m^\prime, m\} \) be the number of coordinates such that \( \theta^r_i = \theta^{r^j}_i = h \) and \( \theta^s_i = \theta^{s^j}_i = l \). There are \( r + 1 \) coordinates with \( \theta^{r^j}_i = h \) and \( s + 1 \) coordinates with \( \theta^{s^j}_i = l \). The utility for agent \( i \) with type \( \theta^j_i \) from announcing \( \theta^{j^j}_i \) is, using the mechanism described above,

\[
\sum_{\theta_{-i} \in \Theta_{-i}} \beta_{-i}(\theta_{-i}) \left[ P^h (\theta_{-i}, m^\prime) [r + 1] m + P^i (\theta_{-i}, m^\prime) \eta (m^\prime) [(s + 1) l + (M - m^\prime - s - 1) h] \right] - t(m^\prime)
\]

where the inequality follows from the assumed monotonicity [i.e. \( P^h (\theta_{-i}, m^\prime) \geq P^i (\theta_{-i}, m^\prime) \) and \( \eta (m^\prime) \leq 1 \). This is a violation of the upwards incentive constraints, a contradiction to the postulate of the Lemma that all upwards incentive constraints hold. Thus, we conclude that a failure of an incentive constraint implies that either \( r = m < m^\prime \) and \( s = M - m^\prime \), in which case an upwards incentive constraint fails or \( r = m^\prime < m \) and \( s = M - m \) in which case a downwards incentive constraint fails.

**Lemma B2** Let \((\rho, \eta, t)\) be an optimal solution to (9). If \((\rho, \eta, t)\) is not ex post efficient, then every downward adjacent incentive constraint and the participation constraint for type-\( l = (l, \ldots, l) \) bind.

**PROOF:** Since by assumption \((\rho, \eta, t)\) is not ex post efficient, it must be the case that \((n - 1) h > nc \). Otherwise, the ex post optimal mechanism is either to provide the public goods if and only if \( \theta^j_i = h \) for all \( i \) when \((n - 1) h < nc < nh \), or to never provide any of the goods when \( nh \leq nc \); in either case, the ex post optimal mechanism is trivially implementable under the constraints in (9). Thus we assume that \((n - 1) h > nc \) in the remainder of the proof.

Suppose that a downward adjacent incentive constraint does not bind, then there exists some \( \theta_i \) such that

\[
\sum_{\theta_{-i} \in \Theta_{-i}} \beta_{-i}(\theta_{-i}) \sum_{j=1}^M \rho^j (\theta) \eta^j_i (\theta_i) \theta^j_i - t_i (\theta_i) > \sum_{\theta_{-i} \in \Theta_{-i}} \beta_{-i}(\theta_{-i}) \sum_{j=1}^M \rho^j (\theta_{-i}, \theta_i l_k) \eta^j_i (\theta_i l_k) \theta^j_i - t_i (\theta_i l_k).
\]
If $\eta_i^j(\theta_i|l_k) < 1$, we can increase $\eta_i^j(\theta_i|l_k)$ slightly without upsetting the constraint. Since $(n-1)h > nc$, it follows that $\sum_{\theta_{-i} \in \Theta_{-i}} \beta_{-i}(\theta_{-i}) \rho_i^j(\theta_{-i}, \theta_i|l_k) > 0$ for every $j$. Hence, an increase in $\eta_i^j(\theta_i|l_k)$ increases the value of the objective function, contradicting the postulated optimality of $(\rho, \eta, t)$. Suppose instead that $\eta_i^j(\theta_i|l_k) = 1$. Then, we can find some $\varepsilon > 0$ and raise the tax to $\tilde{t}_i(\theta_i) = t_i(\theta_i) + \varepsilon$ for $\theta_i$ and every $\theta_i'$ with $m(\theta_i') = m(\theta_i)$. This raises some extra revenue. We can then proceed inductively as follows. First consider types $\theta_i^A$ with $\rho_i^A(\theta_i|l_k) = m(\theta_i) - 2$. If $\eta_i^j(\theta_i^A) < 1$ we can increase the surplus by increasing $\eta_i^j(\theta_i^A)$ for $\theta_i^A$ with $m(\theta_i^A) = m(\theta_i) - 2$ and simultaneously decrease $t_i(\theta_i^B)$ for types with $m(\theta_i^B) = m(\theta_i) - 1$ so as to keep the downward incentive constraint for types with $\theta_i^B$. If $\eta_i^j(\theta_i^A) = 1$ and $m(\theta_i) - 2 \geq 1$ repeat the argument for types $\theta_i^C$ with $m(\theta_i^C) = m(\theta_i) - 3$. The resulting increase in access probabilities is always desirable from the social welfare viewpoint. Thus by induction, we conclude that either there exists a feasible allocation with a higher surplus or that $\eta_i^j(\theta_i) = 1$ for all $\theta_i$ and $j$.

However, if $\eta_i^j(\theta_i) = 1$ for all $\theta_i$ and $j$, i.e., if there are no active use of exclusions in the solution, then the extra revenue from $\tilde{t}_i(\theta_i)$ could be used to improve the surplus by by increasing $\rho_i(\theta_i)$ for some $\theta_i$, since the postulated mechanism $(\rho, \eta, t)$ is not ex post efficient.

The result that the participation constraint for type-$1$ must bind can be proved analogously.

PROOF OF PROPOSITION 2: First note that (18) is irrelevant when $m = M$. Moreover, it is immediate from (21) that the probability of provision given $(h, \theta_{-i})$ is always weakly higher than under $(\theta_i, \theta_{-i})$ for any $\theta_{-i} \in \Theta_{-i}$. Finally, from (18) and (21), we know that a sufficient condition for monotonicity is that $\frac{1}{\beta_m(M-m)} \max \{0, G_m(\Phi)\}$ is increasing in $m$ on $\{0, \ldots, M-1\}$. But,

$$\frac{G_m(\Phi)}{\beta_m(M-m)} = l - \Phi \left[ \frac{(h-1)}{\beta_m(M-m)} \sum_{j=m+1}^{M} \beta_j \right].$$

(B38)

PROOF OF REMARK 1: If valuations are independent across goods, say the probability that an agent has a high valuation for any good $j$ is $\alpha$, then the probability that an agent has $k$ high valuations is given by $\beta_k = \frac{M! \alpha^k (1 - \alpha)^{M-k}}{k!(M-k)!}$. Thus,

$$\beta_{k+1} = \frac{(k+1)! (M-k-1) \alpha^{k+1} (1 - \alpha)^{M-k-1}}{(k+1)(1 - \alpha) \beta_k} = \frac{(M-k) \alpha}{(k+1) (1 - \alpha) \beta_k}. (B39)$$

Using (B39), we have that

$$\frac{1}{\beta_{m+1}(M-m-1)} \sum_{j=m+2}^{M} \beta_j = \frac{1}{\beta_{m+1}(M-m-1)} \sum_{j=m+1}^{M-1} \beta_{j+1} = \frac{(m+1)(1-\alpha)}{(M-m) \alpha (M-m-1)} \beta_m \sum_{j=m+1}^{M-1} \frac{(M-j) \alpha}{(j+1)(1-\alpha) \beta_j} = \frac{1}{(M-m) \beta_m} \sum_{j=m+1}^{M-1} \beta_j < \frac{1}{(M-m) \beta_m} \sum_{j=m+1}^{M} \beta_j,$$

where the inequality follows from the fact that $j \geq m+1$ and $\beta_M > 0$.

PROOF of COROLLARY 1: We need to verify that $G_{m+1}(\Phi) > 0$ is implied by $G_m(\Phi) \geq 0$, and that $G_{m-1}(\Phi) < 0$ is implied by $G_m(\Phi) \leq 0$. Both are immediate from (A12).
PROOF OF LEMMA 6: To prove this lemma, it turns out to be useful to consider a related auxiliary problem which aims to maximize the average probability of provision (instead of social welfare) under the same constraints as the relaxed problem (9):

\[
\max_{\{p, \eta, t\}} \sum_{\theta \in \Theta^n} \beta(\theta) \sum_{j=1}^{M} \rho_j(\theta) \\
\text{s.t. } (10), (4), (5). \tag{B40}
\]

We first show in Claim B3 below that the characterization of the solution to (B40) is qualitatively similar to the constrained welfare problem (9):

Claim B3 Let \((p, \eta, t)\) be an optimal solution to (B40) and assume that \(\sum_{\theta \in \Theta_i} \beta_{-i}(\theta_{-i}) \rho_j(\theta_i, \theta_{-i}) > 0\). Then,

1. conditional on provision, all consumers get access to all their high valuation goods and the inclusion rule for low valuation goods is given by:

\[
\eta_i^j(\theta_i) = \eta(m) \equiv \begin{cases} 
0 & \text{if } G_m(1) < 0 \\
z \in [0,1] & \text{if } G_m(1) = 0 \\
1 & \text{if } G_m(1) > 0;
\end{cases} \tag{B41}
\]

2. there exists some \(\Lambda \geq 0\) such that the provision rule for good \(j\) satisfies

\[
\rho_j(\theta) = \begin{cases} 
0 & \text{if } 1 + \Lambda \sum_{m=0}^{M} \left[ H_j^j(\theta, m) h + L_j^j(\theta, m) \max\{0, G_m(1)\} \right] - cn < 0 \\
z \in [0,1] & \text{if } 1 + \Lambda \sum_{m=0}^{M} \left[ H_j^j(\theta, m) h + L_j^j(\theta, m) \max\{0, G_m(1)\} \right] - cn = 0 \tag{B42}
\end{cases}
\]

Proof of Claim B3: The derivation of the inclusion rules follow the analysis of the constrained welfare problem step by step and is omitted.

To derive the provision rule, note that the optimality conditions for \(\rho_j(\theta)\) associated with the problem (B40) may be written as

\[
\beta(\theta) + \sum_{m=0}^{M} \lambda(m) m \left[ H_j^j(\theta, m) \beta_{-i}(\theta_{-i}) h + L_j^j(\theta, m) \eta(m) \right] \\
- \sum_{m=0}^{M-1} \lambda(m+1) \left\{ H_j^j(\theta, m) \beta_{-i}(\theta_{-i}) (M-m) h + L_j^j(\theta, m) \beta_{-i}(\theta_{-i}) \eta(m) [(M-m) l + (h - l)] \right\} \\
- \Lambda \beta(\theta) cn + \gamma^j(\theta) - \phi^j(\theta) = 0,
\]

together with the complementary slackness conditions. By noting that \(\frac{\beta_{-i}(\theta_{-i})}{\beta(\theta)} = \frac{1}{\beta_i(\theta_i)}\), we can write the condition as

\[
1 + \sum_{m=0}^{M} \lambda(m) \left[ H_j^j(\theta, m) \frac{m}{\beta_i(\theta_i)} h + L_j^j(\theta, m) \frac{m}{\beta_i(\theta_i)} \eta(m) \right] \\
- \sum_{m=0}^{M-1} \lambda(m+1) \left\{ H_j^j(\theta, m) \frac{(M-m)}{\beta_i(\theta_i)} h + L_j^j(\theta, m) \frac{1}{\beta_i(\theta_i)} \eta(m) [(M-m) l + (h - l)] \right\} \\
- \Lambda cn + \frac{\gamma^j(\theta) - \phi^j(\theta)}{\beta(\theta)} = 0.
\]
Collecting terms, we get

\[
1 + \sum_{m=0}^{M} H^j (\theta, m) \left\{ \frac{h}{\beta_i (\theta_i)} [\lambda (m) m - \lambda (m + 1) (M - m)] \right\} + \sum_{m=0}^{M} L^j (\theta, m) \frac{\eta (m)}{\beta_i (\theta_i)} \{ \lambda (m) ml - \lambda (m + 1) [(M - m) l + (h - l)] \} - \Lambda cn + \frac{\gamma^j (\theta) - \phi^j (\theta)}{\beta (\theta)} = 0.
\]

Using the difference equation for the multipliers in (14), we can simplify this further to:

\[
1 + \sum_{m=0}^{M} H^j (\theta, m) h \Lambda + \sum_{m=0}^{M} L^j (\theta, m) \left\{ \Lambda \eta (m) l - \frac{\eta (m)}{\beta_m (M - m)} \lambda (m + 1) (h - l) \right\} - \Lambda cn + \frac{\gamma^j (\theta) - \phi^j (\theta)}{\beta (\theta)} = 0.
\]

Using (A11), we can eliminate \( \lambda (m + 1) \) and get

\[
1 + \sum_{m=0}^{M} H^j (\theta, m) h \Lambda + \sum_{m=0}^{M} L^j (\theta, m) \left\{ \Lambda \eta (m) l - \frac{\eta (m)}{\beta_m (M - m)} \lambda (m + 1) (h - l) \right\} - \Lambda cn + \frac{\gamma^j (\theta) - \phi^j (\theta)}{\beta (\theta)} = 0.
\]

Furthermore,

\[
\Lambda \eta (m) l - \frac{\eta (m) (h - l)}{\beta_m (M - m)} \Lambda \sum_{j=m+1}^{M} \beta_j = \frac{\Lambda \eta (m)}{\beta_m (M - m)} \left[ \beta_m (M - m) l - (h - l) \sum_{j=m+1}^{M} \beta_j \right] = \frac{\Lambda}{\beta_m (M - m)} \max \{0, G_m (1)\},
\]

where \( G_m (\cdot) \) is defined in (17). Substituting this back into (A10) gives

\[
1 + \Lambda \sum_{m=0}^{M} \left[ H^j (\theta, m) h + L^j (\theta, m) \frac{\max \{0, G_m (1)\}}{\beta_m (M - m)} - cn \right] + \frac{\gamma^j (\theta) - \phi^j (\theta)}{\beta (\theta)} = 0.
\]

which, by combining with the complementary slackness conditions, gives the result. \( \blacksquare \)

Before getting into the details of the proof, it is also useful to observe that (B42) can be rewritten as

\[
\rho^j (\theta) = \begin{cases} 
0 & \text{if } 1 + \Lambda \left[ \sum_{i=1}^{n} Z^j (\theta_i) - cn \right] < 0 \\
\eta (z) \in [0, 1] & \text{if } 1 + \Lambda \left[ \sum_{i=1}^{n} Z^j (\theta_i) - cn \right] = 0 \\
1 & \text{if } 1 + \Lambda \left[ \sum_{i=1}^{n} Z^j (\theta_i) - cn \right] > 0,
\end{cases}
\]

where

\[
Z^j (\theta_i) = \begin{cases} 
\frac{h}{\beta_m (M - m)} & \text{if } \theta_i^j = h \\
\max \{0, G_m (1)\} & \text{if } \theta_i^j = l \text{ and } \theta_i^k = h \text{ for exactly } m \text{ goods } k \in J.
\end{cases}
\]

The point with this formulation is that \( \{ Z^j (\theta_i) \}_{i=1}^{n} \) is a sequence of i.i.d. random variables. Observe that \( Z^j (\theta_i) \) is bounded below by 0 and above by \( h \), so the variance is bounded. This allows us to use the central limit theorem to establish a “generalized paradox of voting”, which simply states the intuitively obvious fact that the influence of a single agent approaches zero as the number of agents goes out of bounds. To state this, we will now need to be careful about the fact that the solution depends on the number of agents in the economy, and a mechanism with \( n \) agents will therefore now be denoted by \((\rho_n, \eta_n, t_n)\) and the multiplier on the resource constraint will be denoted by \( \Lambda_n \).
(Proof of Lemma 6, continued): Consider a mechanism that solves (B40) first. As \( Z^j (\theta^i) \in [0, h] \) for every \( \theta^i \in \Theta \), it follows that for any pair \((\theta^i, \theta^j)\) we have

\[
E [\rho_n^j (\theta) | \theta^j] - E [\rho_n^i (\theta) | \theta^i] \leq \Pr \left[ 1 + \Lambda_n \left( h + \sum_{k \neq i} Z^j (\theta_k) - cn \geq 0 \right) \right] - \Pr \left[ 1 + \Lambda_n \left( 0 + \sum_{k \neq i} Z^j (\theta_k) \right) - cn > 0 \right] = \Pr \left[ \frac{1 - cn}{\Lambda_n} - h \leq \sum_{k \neq i} Z^j (\theta_k) \leq \frac{1 - cn}{\Lambda_n} \right].
\]

Let \( \sigma = \text{VAR} \left( Z^j (\theta^i) \right) \). We can then rewrite the probability statement as

\[
\Pr \left[ k_n \leq \frac{\sum_{k \neq i} Z^j (\theta_k) - EZ^j (\theta_i)}{\sigma \sqrt{n - 1}} \leq k_n + \frac{h}{\sigma \sqrt{n - 1}} \right] \leq \frac{1}{\sqrt{2\pi}} \int_{k_n}^{k_n + \epsilon} \exp \left( \frac{y^2}{2} \right) dy + \epsilon
\]

for \( n \geq N \). But, the standard normal is symmetric and single-peaked, so for \( n \geq N \),

\[
\Pr \left[ k_n \leq \frac{\sum_{k \neq i} Z^j (\theta_k) - EZ^j (\theta_i)}{\sigma \sqrt{n - 1}} \leq k_n + \frac{h}{\sigma \sqrt{n - 1}} \right] \leq \frac{1}{\sqrt{2\pi}} \int_{k_n}^{k_n + \epsilon} \exp \left( \frac{y^2}{2} \right) dy + \epsilon \leq \frac{1}{\sqrt{2\pi}} \int_{-h}^{h} \exp \left( \frac{y^2}{2} \right) dy + \epsilon \to 0
\]
as \( \epsilon \to 0 \). The result follows.

For the case in which \( \{\rho_n, \eta_n, t_n\}_{n=1}^{\infty} \) is a sequence from the solution to (9), we replace \( Z^j (\theta^i) \) above with

\[
Z^j_n (\theta_i) = \begin{cases} 
\frac{h}{\max \{0, G_m (\Phi_n)\}} & \text{if } \theta^i_j = h \\
\frac{\max \{0, G_m (\Phi_n)\}}{\beta_m (M - m)} & \text{if } \theta^j_k = h \text{ and } m (\theta_i) = m.
\end{cases}
\]

By choice of subsequences such that \( G_m (\Phi_n) \to G_m^* \), we can approximate \( \frac{\max \{0, G_m (\Phi_n)\}}{\beta_m (M - m)} \) with \( \frac{\max \{0, G_m^*\}}{\beta_m (M - m)} \). The rest of the argument follows the one above step by step.